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|  | Rose-Hulman  Institute of Technology |

Memo

To: Dr. Carlotta Berry

From: Ander A Solorzano \_\_\_\_\_\_\_\_\_\_\_\_\_\_ and Ruffin White \_\_\_\_\_\_\_\_\_\_\_\_\_\_

Class: ECE425 – Mobile Robotics

Date: 1/14/2013

Title: Lab06 – Path Planning (Occupancy Grid and Topological)

**PURPOSE**

The purpose of this lab is to use topological and metric navigation to move the mobile robot (CEENBoT) from a start point to a desired goal location.

**PROCEDURES AND STRATEGY**